

| | |
|---------------|---|
| 8.30 – 9.15 | Key-Note Paper for all Participants Electronics for enabling distributed resources in electrical system - From the State of the Art to Future Trends Benoit Jacquemin, Director System Innovations, Schneider Electric, FRANCE (see introduction page 31) |
| 9.20 – 1.10 | Session IM 3 Control and Sensorless Drives and Stepper Drives Chairman: Wolfgang Papiernik, Siemens, GERMANY |
| IM 3-1 | Comparison of Position-Control Algorithms for Industrial Applications G. Ellis, Danaher Motion, USA |
| IM 3-2 | Closed Loop Control of High Speed Permanent Magnet Synchronous Machines for Industrial Applications J. Kiel, U. Koch, Lust-Antriebstechnik, GERMANY |
| IM 3-3 | Starting of Position-Sensorless Permanent Magnet Synchronous Motors at any Speed T. Frenzke, University Erlangen-Nürnberg, GERMANY |
| 10.50 – 11.10 | Coffee Break |
| IM 3-4 | Identification of the PMSM Initial Rotor Position J. Zhang, University of Arkansas at Little Rock, USA, M. Schroff, Maxon Motor, SWITZERLAND |
| IM 3-5 | A Sensorless Multistage Linear Positioning Drive based on External Rotor Permanent Magnet Synchronous Machines U.-H. Rieder, M. Schroedl, A. Nemecek, Vienna University of Technology, AUSTRIA |
| IM 3-6 | Dynamic Performances Evaluation of Simplified Vector Controlled PM-Hybrid Stepping Motor C. Szasz, Technical University of Cluj, ROMANIA, P. T. Szemes, Tokyo University, JAPAN |
| IM 3-7 | Using Open Loop and Closed Loop Control for High Speed Short Stroke Moves A. Houda, Oriental Motor, JAPAN, D. Jones, Incomotion Associates, USA |
| 1.10 – 2.10 | Lunch, Restaurant CCN West 1 st floor |
| 2.10 – 3.10 | Poster/Dialogue Sessions IM D-3 and IM D-4, CCN West 2nd floor |
| | Control and Sensorless Drives Chairman: Alfredo Vagati, University of Turin, ITALY |
| IM D3-1 | A Simple High Performance Control System of a PMSM without a Speed Sensor M. Eskola, A. Hannuksela, H. Tuusa, Tampere University of Technology, FINLAND |
| | Embedded Controls and Software Tools Chairman: Alfredo Vagati, University of Turin, ITALY |
| IM D4-1 | Holistic Modelling of Drives and Power Systems - A Novel Approach M. Cirstea, De Montfort University, UK |
| IM D4-2 | Novel Caspoc-Based Software for Multilevel Simulation of Switched Reluctance Drives A. Matveev, Technical University Moscow, RUSSIA, P. Van Duijzen, Simulation Research, THE NETHERLANDS |

IM D4-3

Integrated Control - Simulation Design Approach

P. Konrondi, Budapest University, HUNGARY, P.Bauer, Delft University, P.J. van Duijzen, Simulation Research, THE NETHERLANDS

3.10 – 6.00

Session IM 4

Embedded Controls and Software Tools

Chairman: Ted Hopper, MACCON, GERMANY

IM 4-1

System-On-A-Programmable-Chip-Enhanced Solutions for High Performance Servo Drives

J.O. Krah, Kollmorgen Seidel, GERMANY

IM 4-2

A Design Platform optimized for Inner Loop Motor Control

J. Goetz, J. Bonanno; International Rectifier, USA

4.10 – 4.30

Coffee Break

IM 4-3

Current Vector Control for Multi-Machine Systems Entirely based on FPGA

E. Monmasson, University de Cergy-Pontoise, J.P. Louis, ENS Cachan, FRANCE

IM 4-4

Simulation as Appliance for Design and Analysis in the Motiv Engineering

W. Kuhn, Stöber Antriebstechnik, T. Neidhold, ITI, GERMANY

IM 4-5

Rapid Application Development Tool Tesla for Fast Prototyping of Electrical Machines

P. van Duijzen, Simulation Research, THE NETHERLANDS, D. Gospodaric, TRIMERICS, GERMANY