#### **Room Paris**

9:00 - 9:20

Official Opening of the PCIM 2001 Conference for all PCIM participants

9:20 - 10:05

**Key-Note Paper for all PCIM participants** 

### POWER ELECTRONICS SOLUTIONS FOR DISTRIBUTED POWER GENERATION

R. W. Zehringer, P. Joerg, M. Suter, ABB Corp. Research Ltd. SWITZERLAND

Recently there has been a lot of attention in the media and in the industrial circles on the issue of deregulation of power distribution markets. At the same time power shortages often caused by the insufficient transmission capacity together with increasing power quality problems prompted the search for a solution in the form of distributed power generation.

There are several competing technologies in the distributed power generation arena that are believed to offer a solution for many of the today's power quality problems and that fit well in the vision of the deregulated power distribution markets. Some of the most promising technologies in this arena are microturbines, fuel cells, wind power systems and photovoltaic plants. However, in order to utilize the full potential of these technologies a power electronic solution in the form of power conditioning system (PCS) is required almost without an exception.

Therefore, this paper will make a survey for power electronics solutions that quite naturally serve a combined function of an interface to power utility grid, fault protection function and can be configured to serve various power quality functions. In addition, power electronics based PCS systems can be remotely controlled and monitored to allow a real time optimization of power generation and can allow aggregation of distributed power generation resources into a so called "Virtual Utility". Finally, this paper will emphasis new opportunities in application of power electronics solutions that arise from the natural synergy of power electronics systems with the information technologies.

10:05 - 10:25	Coffee Break and moving of conference participants to different sessions

10:25 Starting oral sessions IM1 and IM2 running parallel in different rooms

#### Room London

#### Session IM 1

#### **VARIABLE SPEED AND NEW DRIVE SCHEMES**

Chairman: T. Hopper, MACCON, GERMANY

10:25 - 10:55

LOW COST MACHINE WITH TWO INDEPENDENTLY CONTROLLABLE SHAFTS BASED ON THE DUOMOTOR PRINCIPLE

M. Schrödl, S. Ojak, W. Zukrigl, Vienna University of Technology, AUSTRIA

10:55 - 11:25

COMPACT DRIVE MODULES WITH INTEGRATED DOUBLE COMB-TYPE LINEAR MOTOR UNITS IN USE WITH PARALLEL KINEMATIC MACHINES

F. Götz, H.-J. Wehner, Baumüller GmbH, GERMANY

11:25 - 11:55

HIGH-DYNAMIC AND ACCURATE POSITIONING LINEAR AND REVOLVING DRIVES

P.-K. Budig, EAAT GmbH, GERMANY

11:55 - 12:25	HARMONIC DISTORTION AND REDUCTION TECHNIQUES OF PWM ADJUSTABLE SPEED DRIVES - A COST-BENEFIT ANALYSIS
	S. Hansen, P. Nielsen, P. Thorgersen, Danfoss Drives, DENMARK
Room Zurich	Session IM 2
	INDUSTRIAL NETWORKS, INTERNET APPLICATIONS IN DRIVE SYSTEMS
	Chairman: J. M. Pacas, University - GH Siegen, GERMANY
10:25 – 10:55	HIGH PERFORMANCE SERVO'S ON A FIELDBUS E. Smeets, Nyquist, NETHERLANDS
10:55 - 11:25	THE USE OF CAN & LIN-BASED COMMUNICATIONS NETWORKS IN INDUSTRIAL MOTOR CONTROL APPLICATIONS H. Kreidl, V. Vendeirinho, Motorola, GERMANY
11:25 - 11:55	<b>BRINGING THE INTERNET TO THE MOTOR</b> G. Kupris, Motorola, GERMANY
11:25 – 11:55	LIFE CYCLE MONITORING OF ELECTRICAL DRIVE SYSTEMS U. Koch, Lust Antriebstechnik, A. Middendorf, TU Berlin, H. Griese, Fraunhofer IZM, GERMANY
11:55 - 1:00	Lunch, Restaurant CCN West first floor
1:00 – 2:30	Poster/Dialogue Presentations, CCN West second floor
1:00 – 2:30	Poster/Dialogue Presentations, CCN West second floor  Chairman: H. Knöll, University of Applied Sciences Wuerzburg-Schweinfurt, GERMANY
1:00 – 2:30	Chairman: H. Knöll, University of Applied Sciences
1:00 – 2:30 IM-D1	Chairman: H. Knöll, University of Applied Sciences Wuerzburg-Schweinfurt, GERMANY
	Chairman: H. Knöll, University of Applied Sciences Wuerzburg-Schweinfurt, GERMANY  VARIABLE SPEED AND NEW DRIVE SCHEMES  ANALYSIS OF DYNAMIC STATES IN SATURATED INDUCTION MACHINES WHEN USING im, Us AS STATE VARIABLES
IM-D1	Chairman: H. Knöll, University of Applied Sciences Wuerzburg-Schweinfurt, GERMANY  VARIABLE SPEED AND NEW DRIVE SCHEMES  ANALYSIS OF DYNAMIC STATES IN SATURATED INDUCTION MACHINES WHEN USING im, Ys AS STATE VARIABLES A. Campeanu, S. Enache, I. Vlad, University of Craiova, ROMANIA  LOW-COST INDUCTION DRIVES EMPLOYING STRUCTURAL HARMONIC ELIMINATION METHODS P. Bolognesi, L. Taponecco, University of Pisa, ITALY  TANDEM CONVERTER FED INDUCTION MOTOR DRIVE CONTROLLED WITH RE-CONFIGURABLE VECTOR CONTROL SYSTEM
IM-D1 IM-D2	Chairman: H. Knöll, University of Applied Sciences Wuerzburg-Schweinfurt, GERMANY  VARIABLE SPEED AND NEW DRIVE SCHEMES  ANALYSIS OF DYNAMIC STATES IN SATURATED INDUCTION MACHINES WHEN USING $\underline{i_m},\underline{\Psi}_s$ AS STATE VARIABLES  A. Campeanu, S. Enache, I. Vlad, University of Craiova, ROMANIA  LOW-COST INDUCTION DRIVES EMPLOYING STRUCTURAL HARMONIC ELIMINATION METHODS  P. Bolognesi, L. Taponecco, University of Pisa, ITALY  TANDEM CONVERTER FED INDUCTION MOTOR DRIVE CONTROLLED WITH RE-CONFIGURABLE VECTOR CONTROL

IM-D5	MAGNETIC BEARING-DESIGN AND APPLICATION PK. Budig, EAAT GmbH, GERMANY
	SENSORLESS DRIVES – IDENTIFICATION, ESTIMATION AND CONTROL
IM-D6	DESIGN , DEVELOPMENT AND DSP IMPLEMENTATION OF RECURSIVE NEURO-FUZZY SPEED ESTIMATOR FOR ELECTROMECHANICAL DRIVES A.F.Stronach, P. Vas, N.N. Gerard, P.F.A. MacConnell, University of Aberdeen, UK
IM-D7	INVESTIGATIONS TO THE PARAMETER ACCURACY FOR PARAMETER IDENTIFICATIONS IN INDUCTION MOTORS W. Michalik, Dresden University of Technology, GERMANY
IM-D8	FREQUENCY AUTOTUNE FOR DIGITAL DRIVES O. Kidron, I. Cohen. E. Zilker, Kollmorgen-Servotronix, ISRAEL
IM-D9	EXPERT PHASE ANGLE CONTROL IN A VARIABLE RL LOAD CIRCUIT C. Suciu, L. Dafinca, R. Cámpeanu, Transilvania University, ROMANIA
IM-D10	ACCURACY OF INDUCTANCE AND FLUX MEASUREMENTS IN SENSORLESS PM-MOTORS WITH SATURATED SALIENCES E. Kokornaczyk, KSiPPO, SGGW, POLAND
IM-D11	NEURAL NETWORK BASED OPTIMUM EFFICIENCY CONTROL OF VSI FED SPEED-SENSORLESS IM DRIVE
	I. Kádár, R. Kacsó, S. Halász, Budapest University of Technology and Economics, HUNGARY
2:30	I. Kádár, R. Kacsó, S. Halász, Budapest University of Technology and
2:30  Room London	I. Kádár, R. Kacsó, S. Halász, Budapest University of Technology and Economics, HUNGARY
	I. Kádár, R. Kacsó, S. Halász, Budapest University of Technology and Economics, HUNGARY  Starting oral sessions IM 3
	I. Kádár, R. Kacsó, S. Halász, Budapest University of Technology and Economics, HUNGARY  Starting oral sessions IM 3  Session IM 3  SENSORLESS DRIVES – IDENTIFICATION, ESTIMATION
	I. Kádár, R. Kacsó, S. Halász, Budapest University of Technology and Economics, HUNGARY  Starting oral sessions IM 3  Session IM 3  SENSORLESS DRIVES – IDENTIFICATION, ESTIMATION AND CONTROL

3:35 - 4:00	IMPLEMENTATION OF SENSORLESS INDUCTION AND PERMANENT MAGNET SYNCHRONOUS MOTOR DRIVES USING NATURAL FIELD ORIENTATION P. Vas, M. Rashed, A.K.M. Abdulkader, C. Ng, University of Aberdeen, UK, R. Jonsson, NFO Drives, SWEDEN
4:00 – 4:20	Coffee Break
4:20 - 4:45	SENSORLESS CONTROL SYSTEM OF THE INDUCTION MOTOR J. Guzinski, Technical University of Gdansk, POLAND
4:45 – 5:10	EFFECTIVE SENSORLESS CONTROL FOR GENERAL PURPOSE APPLICATION A. Vagati, M. Pastorelli, P. Guglielmi, Politecnico di Torino, ITALY
5:10 – 5:35	SENSORLESS CONTROL OF BRUSHLESS DC MOTORS USING AN EXTENDED KALMAN ESTIMATOR AND A BACK EMFINTEGRATION ALGORITHM: A COMPARISON P. Minciunescu, T. Flint, F. Moynihan, P. Kettle, Analog Devices, USA
5:35 – 6:00	INDUCTION MOTOR SENSORLESS VECTOR CONTROL ALGORITHMS COMPARISON  A. Dumitrescu, R&D Institute of Electrotechnics, ROMANIA, R. Giuclea, I. Stefan, L. Kreindler, C. Bogus, Politehnica University of Bucharest, ROMANIA, V. Burtea, Delphax A. Xerox Company, CANADA

The PCIM Exhibition runs the whole day from 9:00 – 5:00, ground floor, Hall 12. Make your personal time schedule for the day and reserve time for visiting this worldwide leading PCIM and POWER QUALITY Exhibition.

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8:30 - 9:15

**Key-Note Paper for all PCIM participants** 

#### CONTROL SYSTEM PROTOTYPING, PRODUCTIONIZING AND **TESTING WITH MODERN TOOLS**

H. Hanselmann, F. Schütte, dSpace, GERMANY

Tools for the rapid development of control systems have found strong acceptance in certain industries, especially in the automotive industry. Penetration of tool usage seems to be much weaker in the areas of drives, motion control systems and power electronics. There may be reasons for sticking to more traditional development processes, but one reason should not be the cause - lack of awareness.

This presentation shows what modern tools can do today in the development process, why the automotive industry is so keen on using them and driving their further development, and how early adopters of such new tools and methodologies in the drives, motion control and power electronics industry successfully apply them.

The areas covered are simulation and rapid control prototyping, automatic production code generation and hardware-in-the-loop testing. Automatic production code generation is considered of high potential for complex developments and will receive particular attention.

9:15 – 9:30	Coffee Break and moving of conference participants to different sessions
9:30	Starting oral sessions IM4 and IM5 running parallel in different rooms

#### Room London Session IM 4

#### SERVO AND STEP POSITIONING SYSTEMS - DESIGN AND **APPLICATIONS**

Chairman: W. Papiernik, Siemens AG, GERMANY

CONTROL OF SYNCHRONOUS RELUCTANCE MACHINES 9:30 - 10:00 **INCLUDING CROSS SATURATION** 

A. Kilthau, J.M. Pacas, University-GH Siegen, GERMANY

HIGH PERFORMANCE SERVO DRIVE DESIGN FOR 10:00 -10:30 **DISTRIBUTED MOTION CONTROL** 

D. Jouve, D. Bui, Infranor, FRANCE

10:30 - 11:00 Coffee Break

HIGH PERFORMANCE CURRENT CONTROL OF THREE-PHASE 11:00 - 11:30 **BRUSHLESS DC DRIVES WITH DC-LINK CURRENT MEASUREMENT** 

J. Zhang, M. Schroff, Maxon Motor, SWITZERLAND

**COGGING TORQUE COMPARISON BETWEEN 2 AND 3 PHASE** 11:30 - 12:00 **HB TYPE STEPPING MOTORS** 

M. Sakamoto, Japan Servo, JAPAN

Room Zurich	Session IM 5
	LOW POWER MOTORS, ACTUATORS AND DRIVES, CONSUMER APPLICATIONS
	Chairman: A. Vagati, University of Turin, ITALY
9:30 - 10:00	COST OPTIMIZE CONTROL SOLUTION FOR CONSUMER DRIVE A. Denais, A. Jansen, L. Lorenz, Infineon Technologies, GERMANY
10:00 – 10:30	LOW-NOISE, SENSORLESS COMMUTATION OF BRUSHLESS DC MOTORS  J. Krotsch, A. Lelkes, T. Zoller, ebm Werke GmbH, GERMANY
10 :30 – 11 :00	Coffee Break
11:00 - 11:30	NOVEL BRAKE CONCEPT OF VSI-FED SENSORLESS PERMANENT MAGNET SYNCHRONOUS DRIVES E. Robeischl, M. Schrödl, U.H. Rieder, Vienna University of Technology, AUSTRIA
11:30 - 12:00	LOW COST LINEAR VOICE COIL ACTUATOR AS A BI-DIRECTIONAL LONG STROKE PROPORTIONAL SOLENOID M. Godkin, BEI Technologies, USA
12:00 – 1:00	Lunch, Restaurant CCN West first floor
1:00 – 2:30	Poster/Dialogue Presentations, CCN West second floor
	Chairman: S. Colombi, IMV Invertomatic Technology, SWITZERLAND
	SERVO AND STEP POSITIONING SYSTEMS – DESIGN AND APPLICATION
IM-D12	TORQUE CONTROLLER MODEL FOR INDUSTRIAL ROBOT P. Ph. Robet, I.U.T. de Nantes, M. Gautier, Institut de Recherche en Cybernétique de Nantes, FRANCE
IM-D13	SPEED CONTROL BASED ON A POSITION REGULATOR AND AN INCREMENTAL ENCODER J. Zhang, M. Schroff, Maxon Motor, SWITZERLAND
IM-D14	ESTIMATION OF THE MECHANICAL PARAMETERS OF A STIFF THREE-INERTIA-DRIVE  I. Müller, Technical University Darmstadt, GERMANY
	LOW POWER MOTORS, ACTUATORS AND DRIVES, CONSUMER APPLICATIONS
IM-D15	ANALYSIS OF TORQUE RIPPLE IN BRUSHLESS DC MOTOR H. Zeroug, University of Sciences and Technology, ALGERIA

IM-D16	<b>EMC VALIDATION OF THE SAFETY OF SMALL SERVODRIVES</b> T. Missala, Industrial Research Institute for Automation and Measurement, Warszawa, POLAND
IM-D17	AN IMPROVED PERFORMANCE ANALYSIS OF SHADED POLE MOTOR V. Sarac, L. Petkovska, M. Cundev, Sts. Cyril & Methodius University, MACEDONIA
	SOFTWARE TOOLS AND CONTROL HARDWARE
IM-D18	ICS FOR REAL TIME MOTION CONTROL: A DESIGN METHODOLOGY FOR RAPID PROTOTYPING P. Poure, F. Aubépart, F. Braun, Laboratoire LEPSI, FRANCE
IM-D19	ON THE USE OF A DOMAIN DECOMPOSITION ALGORITHM IN THE FINITE ELEMENT ANALYSIS OF ELECTRICAL MACHINES E. Schmidt, Vienna University of Technology, AUSTRIA
IM-D20	AN INTEGRATED C.A.D. ENVIRONMENT FOR DESIGNING AND SIMULATING DOUBLE SALIENT PERMANENT MAGNET LINEAR MOTORS L. Szabó, IA. Viorel, Technical University of Cluj, ROMANIA
2:30	Starting oral sessions IM6 and IM7 running parallel in different rooms
Room London	Consider IM C
Nooni London	Session IM 6
Noom London	MECHATRONIC SYSTEMS
Noom London	
2:30 – 3:15	MECHATRONIC SYSTEMS
	MECHATRONIC SYSTEMS  Chairman: G. Pfaff, University of Erlangen-Nuremberg, GERMANY  KEY-NOTE PAPER  MECHATRONIC SYSTEMS – FROM THE STATE OF THE ART  TO FUTURE TRENDS
2:30 – 3:15	MECHATRONIC SYSTEMS  Chairman: G. Pfaff, University of Erlangen-Nuremberg, GERMANY  KEY-NOTE PAPER  MECHATRONIC SYSTEMS – FROM THE STATE OF THE ART  TO FUTURE TRENDS  D. Schröder, Technical University of Munich, GERMANY  LINEAR H <sub>\infty</sub> CONTROL OF A NONLINEAR TWO-MASS SYSTEM
2:30 - 3:15 3:15 - 3:40	MECHATRONIC SYSTEMS  Chairman: G. Pfaff, University of Erlangen-Nuremberg, GERMANY  KEY-NOTE PAPER  MECHATRONIC SYSTEMS – FROM THE STATE OF THE ART  TO FUTURE TRENDS  D. Schröder, Technical University of Munich, GERMANY  LINEAR H <sub>∞</sub> CONTROL OF A NONLINEAR TWO-MASS SYSTEM  K. Peter, I. Schöling, B. Orlik, IALB Universität Bremen, GERMANY
2:30 - 3:15 3:15 - 3:40 3:40 -4:00	MECHATRONIC SYSTEMS  Chairman: G. Pfaff, University of Erlangen-Nuremberg, GERMANY  KEY-NOTE PAPER  MECHATRONIC SYSTEMS − FROM THE STATE OF THE ART  TO FUTURE TRENDS  D. Schröder, Technical University of Munich, GERMANY  LINEAR H <sub>∞</sub> CONTROL OF A NONLINEAR TWO-MASS SYSTEM  K. Peter, I. Schöling, B. Orlik, IALB Universität Bremen, GERMANY  Coffee Break  ANALYSIS AND CURES FOR MECHANICAL RESONANCE IN INDUSTRIAL SERVO SYSTEMS

5:15 – 5:40	DESIGN OF THE MECHATRONIC SYSTEM WITH LINEAR MOTOR E.A. Lomonova, Joint-Stock Company SpecRemont, RUSSIA, M.J. Ruminchev, S.I. Volsky, Delft University of Technology, NETHERLANDS
Room Zurich	Session IM 7
	SOFTWARE TOOLS AND CONTROL HARDWARE
	Chairman: P. Vas, University of Aberdeen, UK
2:30 - 2:55	CONTRIBUTION TO SYSTEM-ON-CHIP IN MOTION CONTROL: VLSI DESIGN OF A DIGITAL CONTROLLER FOR AN INDUCTION MACHINE F. Aubépart, IMT Technopole, P. Poure, F. Braun, Laboratoire LEPSI, FRANCE
2:55 - 3:20	A NOVEL APPROACH OF MODELING SR MOTOR SYSTEMS U. Bock, Simec, GERMANY
3:20 – 3:45	Coffee Break
3:45 - 4:10	DEVELOPING A CONTROL ASIC FOR HIGHER VOLUME FIVE PHASE HYBRID STEP MOTOR-DRIVE SYSTEMS K. Takahashi, Sanken Electric, JAPAN, K. Moritake, Oriental Motor, JAPAN, D. Jones, Incremotion Associates, USA
4:10 – 4:35	ASIC FOR INDIRECT VECTOR CONTROL OF INDUCTION MOTORS WITH FUZZY LOGIC BASED SPEED REGULATION J.L. Mora, F. Barrero, E. Galván, F. Colodro, J.N. Tombs, A. Torralba, L.G. Franquelo, Escuela Superior de Ingenieros, SPAIN, M. Barranco, Dept. I & D Mecanismos y Accesorios
4:35 – 5:00	VIRTUAL SYSTEM LAB – A MONITOR CONTROL SIMULATION ENVIRONMENT AVAILABLE THROUGH WWW Vecera, Motorola Czech Systems Lab, CZECH REPUBLIK, M. Brejl, A. Lara, Motorola SPS, POLAND
5:00 - 5:25	MATCHING WINDING PATTERNS TO MAGNET SHAPES IN SMALLER BRUSHLESS PM SERVO MOTORS D. Jones, Incremotion Associates, USA
5:25 - 5:50	COMPARISON OF ANALYTICAL AND FEM CALCULATION SOFTWARE AS A TOOL FOR DESIGNING A HIGH EFFICIENT INDUCTION MACHINE P. Pichler, P. Ebner, H. Weiss, University of Leoben, AUSTRIA
6:00	Get Together Party

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#### **Room Paris**

8:30 - 9:15

10:20 - 10:50

Coffee Break

#### **Key-Note Paper for all PCIM participants**

# KEY DEVELOPMENTS FOR SUPERCAPACITIVE ENERGY STORAGE: POWER ELECTRONIC CONVERTERS, SYSTEMS AND CONTROL

A. Rufer, Laboratoire d'Electronique Industrielle LEI, EPFL, SWITZERLAND

Supercapacitors represent one of the newest innovations in the field of electrical energy storage, and will find their place in many applications where energy storage is needed, and can help to the smoothing of strong and short time power solicitations of a distribution network. Other system developments are going on, opening new fields in engineering sciences, based on new possibilities in the field of electrical energy storage.

In comparison with classical capacitors, these new components allow a much more higher energy density, together with a high power density. Even if the energy density is not comparable with that one of electrochemical accumulators, the possible energy amount and storage time is compatible with many industrial requirements. In transportation systems, as a first example, the energy needed to relay two bus-stations can easily be transferred from a fixed supercapacitive storage device to another mobile one placed on the bus during passenger transfer time, allowing so the use of electrical propulsion without trolleys. Many other systems for better share of energy and instantaneous power amounts will soon appear as industrial products.

This contribution shows some actual research and development projects, running at university level, but in connection with specialists from the corresponding application field. Innovative and promising solutions and technologies are investigated, which need of course clarification of their actual industrial and economical compatibility, they can also be seen as future solutions for next decades, in relation with the tendency of getting weaker distribution of electrical energy.

9:15 – 9:30	Coffee Break and moving of conference participants to different sessions	
9:30	Starting oral sessions IM8 and IM9 running parallel in different rooms	
Room London	Session IM 8	
	TRACTION AND ELECTRIC VEHICLES	
	Chairman: S. Chiama, Consultant ABB, ITALY	
9:30 – 9:55	ASYNCHRONOUS LINEAR MACHINE WITH MASSIVE IRON AS SECONDARY Th. Werle, M. Hofmann, A. Binder, Darmstadt University of Technology, GERMANY	
9:55 - 10:20	ENERGY SAVING WITH HIGH SPEED TRAINS PROPELLED BY DIRECT PERMANENT MAGNET SYNCHRONOUS DRIVE	

Th. Koch, A. Binder, Darmstadt University of Technology, GERMANY

11:15 - 11:40 COMMERCIAL ELECTRONIC DEVICES FOR OPERATION IN HIGH-PRESSURE; DEEP-SEA DRIVE SYSTEM P. Snary, C.M. Bingham, D. A. Stone, University of Sheffield, UK  11:40 - 12:05 CRITERIA FOR INDIVIDUATING THE TRACTION SPECIFICATIONS AND DESIGNING THE MOTOR OF AN ELECTRICAL SCOOTER N. Bianchi, S. Bolognani, F. Luise, University of Padova, ITALY  12:05 - 12:30 ENERGY-FLOW-CONTROL OF A HYBRID-CAR PK. Budig, EAAT GmbH, GERMANY  Room Zurich Session IM 9  IMPROVEMENTS IN MODULATION AND DIRECT TORQUE CONTROL  Chairman: G. Ellis, Kollmorgen, USA  9:30 - 9:55 IMPROVED SINGLE CURRENT SENSING METHOD AND ITS REALISATION BASED ON ADMCF341 DSP CONTROLLER B. Huo, T. Flint, F. Moyrnihan, Analog Devices, USA  9:55 - 10:20 STEADY-STATE ANALYSIS OF AN ORIGINAL SVM-DTC STRATEGY FOR INDUCTION MOTOR DRIVES E. Monmasson, A. A. Naassani, Université de Cergy-Pontoise, J. P. Louis, ENS Cachan, FRANCE  10:20 - 10:50 Coffee Break  10:50 - 11:15 IMPROVEMENTS IN FLUX AND TORQUE CONTROL IN DTC INDUCTION MOTOR DRIVES W. S. H. Wong, D. Holliday, University of Bristol, UK  11:15 - 11:40 TORQUE AND SPEED CONTROL OF INVERTER-FED INDUCTION MACHINE USING SLIDING MODE F. Moldoveanu, V. Comnac, M. Cernat, Transilvania University of Brasov, ROMANIA	10:50 – 11:15	NOVEL BRUSHLESS ELECTRIC MOTOR DRIVES IN VEHICLE APPLICATION T. Mezo, S. Peresztegi, P. Korondi, L. Nagy, HUNGARY
SPECIFICATIONS AND DESIGNING THE MOTOR OF AN ELECTRICAL SCOOTER N. Bianchi, S. Bolognani, F. Luise, University of Padova, ITALY  12:05 – 12:30 ENERGY-FLOW-CONTROL OF A HYBRID-CAR PK. Budig, EAAT GmbH, GERMANY  Room Zurich Session IM 9  IMPROVEMENTS IN MODULATION AND DIRECT TORQUE CONTROL  Chairman: G. Ellis, Kollmorgen, USA  9:30 – 9:55 IMPROVED SINGLE CURRENT SENSING METHOD AND ITS REALISATION BASED ON ADMCF341 DSP CONTROLLER B. Huo, T. Flint, F. Moynihan, Analog Devices, USA  9:55 – 10:20 STEADY-STATE ANALYSIS OF AN ORIGINAL SVM-DTC STRATEGY FOR INDUCTION MOTOR DRIVES E. Monmasson, A. A. Naassani, Université de Cergy-Pontoise, J. P. Louis, ENS Cachan, FRANCE  10:20 – 10:50 Coffee Break  10:50 - 11:15 IMPROVEMENTS IN FLUX AND TORQUE CONTROL IN DTC INDUCTION MOTOR DRIVES W. S. H. Wong, D. Holliday, University of Bristol, UK  11:15 – 11:40 TORQUE AND SPEED CONTROL OF INVERTER-FED INDUCTION MACHINE USING SLIDING MODE F. Moldoveanu, V. Comnac, M. Cernat, Transilvania University of Brasov, ROMANIA	11:15 - 11:40	COMMERCIAL ELECTRONIC DEVICES FOR OPERATION IN HIGH-PRESSURE; DEEP-SEA DRIVE SYSTEM
Room Zurich  Session IM 9  IMPROVEMENTS IN MODULATION AND DIRECT TORQUE CONTROL  Chairman: G. Ellis, Kollmorgen, USA  9:30 – 9:55  IMPROVED SINGLE CURRENT SENSING METHOD AND ITS REALISATION BASED ON ADMCF341 DSP CONTROLLER B. Huo, T. Flint, F. Moynihan, Analog Devices, USA  9:55 – 10:20  STEADY-STATE ANALYSIS OF AN ORIGINAL SVM-DTC STRATEGY FOR INDUCTION MOTOR DRIVES E. Monmasson, A. A. Naassani, Université de Cergy-Pontoise, J. P. Louis, ENS Cachan, FRANCE  10:20 – 10:50  Coffee Break  10:50 - 11:15  IMPROVEMENTS IN FLUX AND TORQUE CONTROL IN DTC INDUCTION MOTOR DRIVES W. S. H. Wong, D. Holliday, University of Bristol, UK  11:15 – 11:40  TORQUE AND SPEED CONTROL OF INVERTER-FED INDUCTION MACHINE USING SLIDING MODE F. Moldoveanu, V. Comnac, M. Cernat, Transilvania University of Brasov, ROMANIA	11:40 – 12:05	SPECIFICATIONS AND DESIGNING THE MOTOR OF AN ELECTRICAL SCOOTER
IMPROVEMENTS IN MODULATION AND DIRECT TORQUE CONTROL  Chairman: G. Ellis, Kollmorgen, USA  9:30 – 9:55  IMPROVED SINGLE CURRENT SENSING METHOD AND ITS REALISATION BASED ON ADMCF341 DSP CONTROLLER B. Huo, T. Flint, F. Moynihan, Analog Devices, USA  9:55 – 10:20  STEADY-STATE ANALYSIS OF AN ORIGINAL SVM-DTC STRATEGY FOR INDUCTION MOTOR DRIVES E. Monmasson, A. A. Naassani, Université de Cergy-Pontoise, J. P. Louis, ENS Cachan, FRANCE  10:20 – 10:50  Coffee Break  10:50 - 11:15  IMPROVEMENTS IN FLUX AND TORQUE CONTROL IN DTC INDUCTION MOTOR DRIVES W. S. H. Wong, D. Holliday, University of Bristol, UK  11:15 – 11:40  TORQUE AND SPEED CONTROL OF INVERTER-FED INDUCTION MACHINE USING SLIDING MODE F. Moldoveanu, V. Comnac, M. Cernat, Transilvania University of Brasov, ROMANIA	12:05 – 12:30	
CONTROL  Chairman: G. Ellis, Kollmorgen, USA  9:30 – 9:55  IMPROVED SINGLE CURRENT SENSING METHOD AND ITS REALISATION BASED ON ADMCF341 DSP CONTROLLER B. Huo, T. Flint, F. Moynihan, Analog Devices, USA  9:55 – 10:20  STEADY-STATE ANALYSIS OF AN ORIGINAL SVM-DTC STRATEGY FOR INDUCTION MOTOR DRIVES E. Monmasson, A. A. Naassani, Université de Cergy-Pontoise, J. P. Louis, ENS Cachan, FRANCE  10:20 – 10:50  Coffee Break  10:50 - 11:15  IMPROVEMENTS IN FLUX AND TORQUE CONTROL IN DTC INDUCTION MOTOR DRIVES W. S. H. Wong, D. Holliday, University of Bristol, UK  11:15 – 11:40  TORQUE AND SPEED CONTROL OF INVERTER-FED INDUCTION MACHINE USING SLIDING MODE F. Moldoveanu, V. Comnac, M. Cernat, Transilvania University of Brasov, ROMANIA	Room Zurich	Session IM 9
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INDUCTION MACHINE USING SLIDING MODE F. Moldoveanu, V. Comnac, M. Cernat, Transilvania University of Brasov, ROMANIA	10:50 - 11:15	INDUCTION MOTOR DRIVES
11:40 - 1:30 Lunch, Restaurant CCN West first floor	11:15 – 11:40	INDUCTION MACHINE USING SLIDING MODE F. Moldoveanu, V. Comnac, M. Cernat, Transilvania University of Brasov,
	11:40 - 1:30	Lunch, Restaurant CCN West first floor

1:30	Starting oral session IM10
Room London	Session IM 10
	MOTION COMPONENTS - SENSORS AND ACTUATORS
	Chairman: D. Jones, Incremotion, USA
1:30 – 1:55	SUPPRESSION OF SYSTEMATIC ERRORS IN RESOLVER SIGNALS FOR HIGH PERFORMANCE SERVO DRIVES A. Bünte, S. Beineke, Lust Antriebstechnik, GERMANY
1:55 – 2:20	USE OF OBSERVERS TO PROCESS RESOLVER SIGNALS IN INDUSTRIAL SERVO SYSTEMS G. Ellis, J. Krah, Kollmorgen, USA
2:20 – 2:40	Coffee Break
2:40 - 3:05	DESIGN AND SIMULATION OF A LINEAR ACTUATOR FOR DIRECT DRIVE  E. Macua, Ch. Ripoll, Renault, JC. Vannier, Ecole Superieure d'Electricitié, FRANCE
3:05 – 3:30	X-Y CONTACTLESS POSITION SENSING USING MOVING MAGNETS S. Biwersi, D. Angleviel, D. Frachon, Moving Magnet Technologies, FRANCE

The PCIM Exhibition runs the whole day from 9:00 – 5:00, ground floor, Hall 12. Make your personal time schedule for the day and reserve time for visiting this worldwide leading PCIM and POWER QUALITY Exhibition.