

SKHI 21 A, SKHI 22 A / B

Absolute Maximum Ratings					
Symbol	Term		Values	Units	
V_S	Supply voltage prim.		18	V	
V_{IH}	Input signal volt. (High)	SKHIxxA	$V_S + 0,3$	V	
		SKHI22B	$5 + 0,3$	V	
$I_{outPEAK}$	Output peak current		8	A	
$I_{outAVmax}$	Output average current		40	mA	
f_{max}	max. switching frequency		50	kHz	
V_{CE}	Collector emitter voltage sense across the IGBT		1700	V	
dv/dt	Rate of rise and fall of voltage secondary to primary side		50	kV/ μ s	
V_{isolIO}	Isolation test voltage	Standard	2500	V _{ac}	
	input-output (1 min.AC)	Version „H4“	4000	V _{ac}	
V_{isol12}	Isolation test voltage output 1 - output 2 (1 min.AC)		1500	V	
R_{Gonmin}	Minimum rating for R_{Gon}		3	Ω	
$R_{Goffmin}$	Minimum rating for R_{Goff}		3	Ω	
$Q_{out/pulse}$	Max. rating for output charge per pulse		4 ¹⁾	μ C	
T_{op}	Operating temperature		- 40... + 85	$^{\circ}$ C	
T_{stg}	Storage temperature		- 40... + 85	$^{\circ}$ C	

SEMIKRON® Hybrid Dual IGBT Driver SKHI 22 A / B

- Double driver for halfbridge IGBT modules
- SKHI 22 A/B H4 is for 1700 V-IGBT
- SKHI 22 A is compatible to old SKHI 22
- SKHI 22 B has additional functionality

Hybrid Dual MOSFET Driver SKHI 21 A

- drives MOSFETs with $V_{DS(on)} < 10$ V
- is compatible to old SKHI 21

Preliminary Data

Electrical Characteristics ($T_a = 25^{\circ}$ C)						
Symbol	Term		Values			Units
			min.	typ.	max.	
V_S	Supply voltage primary side		14,4	15	15,6	V
I_{SO}	Supply current primary side (no load)		–	80	–	mA
	Supply current primary side (max.)		–	–	290	mA
V_i	Input signal voltage	SKHIxxA on/off	–	15 / 0	–	V
		SKHI22B on/off	–	5 / 0	–	V
V_{iT+}	Input threshold voltage (High)	SKHIxxA	10,9	11,7	12,5	V
		SKHI22B	3,5	3,7	3,9	V
V_{iT-}	Input threshold voltage (Low)	SKHIxxA	4,7	5,5	6,5	V
		SKHI22B	1,5	1,75	2,0	V
R_{in}	Input resistance	SKHIxxA	–	10	–	k Ω
		SKHI22B	–	3,3	–	k Ω
$V_{G(on)}$	Turn on gate voltage output		–	+15	–	V
$V_{G(off)}$	Turn off gate voltage output	SKHI22x	–	-7	–	V
		SKHI21A	–	0	–	V
R_{GE}	Internal gate-emitter resistance		–	22	–	k Ω
f_{ASIC}	Asic system switching frequency		–	8	–	MHz
$t_{d(on)IO}$	Input-output turn-on propagation time		0,85	1	1,15	μ s
$t_{d(off)IO}$	Input-output turn-off propagation time		0,85	1	1,15	μ s
$t_{d(err)}$	Error input-output propagation time		–	0,6	–	μ s
$t_{pERRRESET}$	Error reset time		–	9	–	μ s
t_{TD}	Top-Bot Interlock Dead Time	SKHI22x	3,3	–	4,3	μ s
		SKHI21A	0	–	4,3	μ s
V_{CEstat}	Reference voltage for V_{CE} -monitoring		–	5 ²⁾	10	V
			–	6 ³⁾	10	V
C_{ps}	Coupling capacitance primary secondary		–	12	–	pF
MTBF	Mean Time Between Failure $T_a = 40^{\circ}$ C		–	2,0	–	10^6 h
m	weight		–	45	–	g

Features

- CMOS compatible inputs
- Short circuit protection by V_{CE} monitoring and switch off
- Drive interlock top/bottom
- Isolation by transformers
- Supply undervoltage protection (13 V)
- Error latch/output

Typical Applications

- Driver for IGBT and MOSFET modules in bridge circuits in choppers, inverter drives, UPS and welding inverters
- DC bus voltage up to 1000V

1) see fig. 6

2) At $R_{CE} = 18$ k Ω , $C_{CE} = 330$ pF

3) At $R_{CE} = 36$ k Ω , $C_{CE} = 470$ pF, $R_{VCE} = 1$ k Ω

External Components

Component	Function	Recommended Value
R _{CE}	Reference voltage for V _{CE} -monitoring $V_{CEstat}(V) = \frac{10 \cdot R_{CE}(k\Omega)}{10 + R_{CE}(k\Omega)} - 1,4 \quad (1)$ with R _{VCE} = 1kΩ (1700V IGBT): $V_{CEstat}(V) = \frac{10 \cdot R_{CE}(k\Omega)}{10 + R_{CE}(k\Omega)} - 1,8 \quad (1.1)$	10kΩ < R _{CE} < 100kΩ 18kΩ for SKM XX 123 (1200V) 36kΩ for SKM XX 173 (1700V)
C _{CE}	Inhibit time for V _{CE} - monitoring $t_{min} = \tau_{CE} \cdot \ln \left[\frac{15 - V_{CEstat}(V)}{10 - V_{CEstat}(V)} \right] \quad (2)$ $\tau_{CE}(\mu s) = C_{CE}(nF) \cdot \frac{10 \cdot R_{CE}(k\Omega)}{10 + R_{CE}(k\Omega)} \quad (3)$	C _{CE} < 2,7nF 0,33nF for SKM XX 123 (1200V) 0,47nF for SKM XX 173 (1700V) 0,5μs < t _{min} < 10μs
R _{VCE}	Collector series resistance for 1700V IGBT-operation	1kΩ / 0,4W
R _{ERROR}	Pull-up resistance at error output $\frac{U_{Pull-U_p}}{R_{ERROR}} < 15mA$	1kΩ < R _{ERROR} < 10kΩ
R _{GON}	Turn-on speed of the IGBT ⁴⁾	R _{GON} > 3Ω
R _{GOFF}	Turn-off speed of the IGBT ⁵⁾	R _{GOFF} > 3Ω

⁴⁾ Higher resistance reduces free-wheeling diode peak recovery current, increases IGBT turn-on time.

⁵⁾ Higher resistance reduces turn-off peak voltage, increases turn-off time and turn-off power dissipation

SKHI 21 A, SKHI 22 A / B

PIN array

Fig. 2 shows the pin arrays. The input side (primary side) comprises 10 inputs (SKHI 22A / 21A 8 inputs), forming the interface to the control circuit (see fig.1).

The output side (secondary side) of the hybrid driver shows two symmetrical groups of pins with 4 outputs, each forming the interface to the power module. All pins are designed for a grid of 2,54 mm.

Primary side PIN array

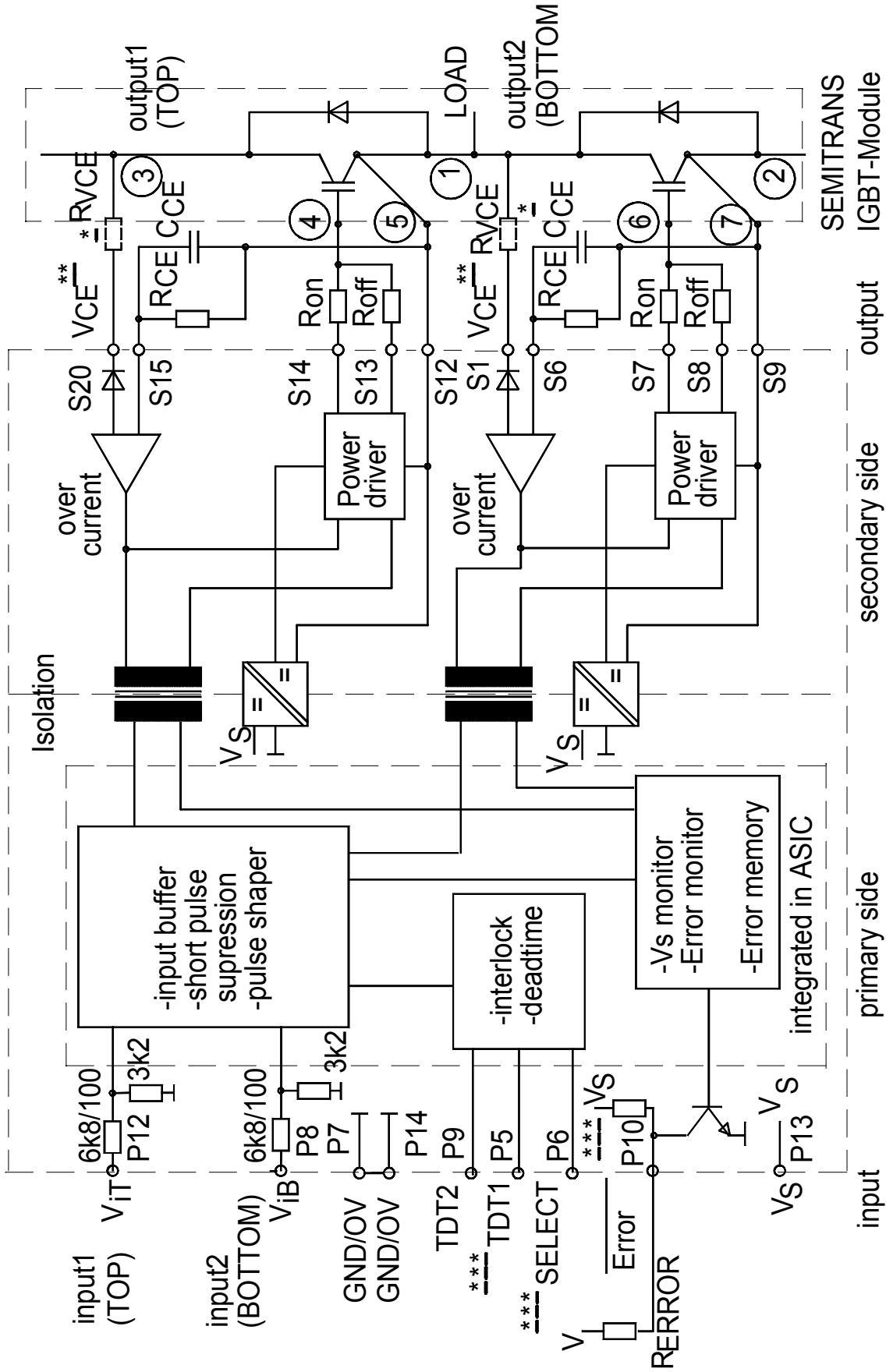
PIN No.	Designation	Explanation
P14	GND / 0V	related earth connection for input signals
P13	V _S	+ 15V ± 4% voltage supply
P12	V _{IN1}	switching signal input 1 (TOP switch) positive 5V logic (for SKHI22A /21A, 15V logic)
P11	free	not wired
P10	/ERROR	error output, low = error; open collector output; max 30V / 15mA (for SKHI22A /21A, internal 10kΩ pull-up resistor versus V _S)
P9	TDT2	signal input for digital adjustment of interlocking time; SKHI22B: to be switched by bridge to GND (see fig. 3) SKHI22A /21A: to be switched by bridge to V_S
P8	V _{IN2}	switching signal input 2 (BOTTOM switch); positive 5V logic (for SKHI22A /21A, 15V logic)
P7	GND / 0V	related earth connection for input signals
P6	SELECT	signal input for neutralizing locking function; to be switched by bridge to GND
P5	TDT1	signal input for digital adjustment of locking time; to be switched by bridge to GND

ATTENTION: Inputs P6 and P5 are not existing for SKHI 22A/ 21A. The contactor tracks of the digital input signals P5/ P6/ P9 must not be longer than 20 mm to avoid interferences, if no bridges are connected.

Secondary side PIN array

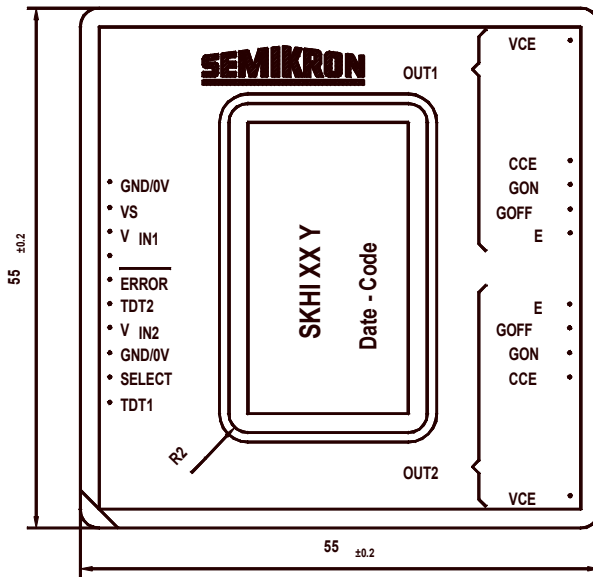
PIN No.	Designation	Explanation
S20	V _{CE1}	collector output IGBT 1 (TOP switch)
S15	C _{CE1}	reference voltage adjustment with R _{CE} and C _{CE}
S14	G _{ON1}	gate 1 R _{ON} output
S13	G _{OFF1}	gate 1 R _{OFF} output
S12	E1	emitter output IGBT 1 (TOP switch)
S1	V _{CE2}	collector output IGBT 2 (BOTTOM switch)
S6	C _{CE2}	reference voltage adjustment with R _{CE} and C _{CE}
S7	G _{ON2}	gate 2 R _{ON} output
S8	G _{OFF2}	gate 2 R _{OFF} output
S9	E2	emitter output IGBT 2 (BOTTOM switch)

ATTENTION: The connector leads to the power module should be as short as possible.



* When SKHI22B is driving 1700V IGBTs, a $1k\Omega / 0.4W$ R_{VCE} -resistor must be connected in series to the V_{CE} input.
 ** The V_{CE} -terminal is to be connected to the IGBT collector C. If the V_{CE} -monitoring is not used, connect S1 to S9 or S20 to S12 respectively.
 *** Terminals P5 and P6 are not existing for SKHI22A/21A; internal pull-up resistor exists in SKHI22A/21A only.
 1-7 Connections to SEMITRANS GB-module

Fig. 1 Block diagram of SKHI 22 A / B / 21 A



detail "A" on scale 10 : 1

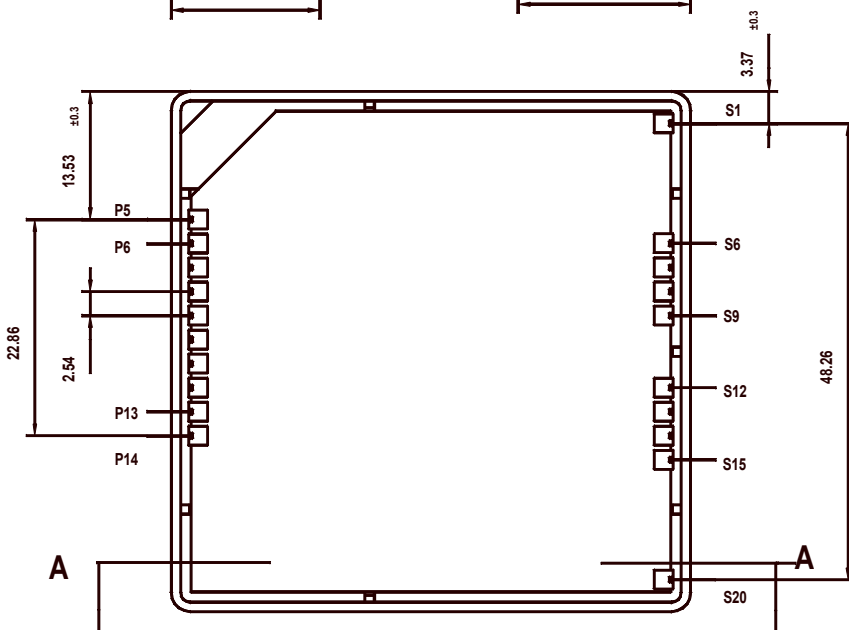
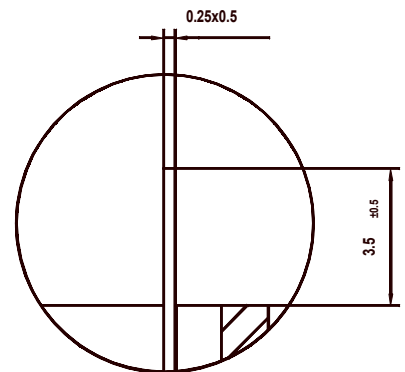
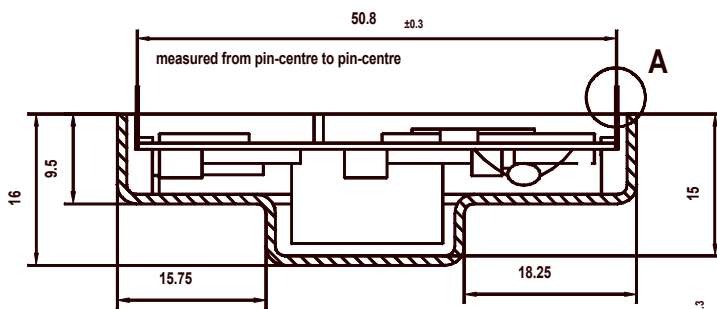


Fig. 2 Dimension drawing and PIN array (P5 and P6 are not existing for SKHI22A/21A)

SEMIDRIVER®

SKHI 22A / 22B und SKHI 21A

Hybrid dual drivers

The driver generation SKHI 22A/B and SKHI 21A will replace the hybrid drivers SKHI 21/22 and is suitable for all available low and medium power range IGBT and MOSFETs.

The SKHI 22A (SKHI 21A) is a form-, fit- and mostly function-compatible replacement to its predecessor, the SKHI 22 (SKHI 21).

The SKHI 22B is recommended for any new development. It has two additional signal pins on the primary side with which further functions may be utilized.

The SKHI 22A and SKHI 22B are available with standard isolation (isolation testing voltage 2500 VAC, 1min) as well as with an increased isolation voltage (type "H4") (isolation testing voltage 4000 VAC, 1min). The SKHI 21A is only offered with standard isolation features.

Differences SKHI 22-22A (SKHI 21-21A)

Compared to the old SKHI 22/21 the new driver SKHI 22A / 21A is absolutely compatible with regards to pins and mostly with regards to functions. It may be equivalently used in existing PCBs.

The following points have to be considered when exchanging the drivers:

- Leave out the two resistors RTD for interlocking dead time adjustment at pin 11 and pin 9.
- The interlocking time of the driver stages in halfbridge applications is adjusted to 3,25 µs. It may be increased up to 4,25 µs by applying a 15 V (VS) supply voltage at Pin 9 (TDT2) (wire bridge)
- The error reset time is typically 9µs.
- The input resistance is 10 kΩ.

As far as the SKHI 22A is concerned, the negative gate voltage required for turn-off of the IGBT is no longer -15V, but -7V.

General description

The new driver generation SKHI 22A/B, SKHI 21A consists of a hybrid component which may directly be mounted to the PCB.

All devices necessary for driving, voltage supply, error monitoring and potential separation are integrated in the driver. In order to adapt the driver to the used power module, only very few additional wiring may be necessary.

The forward voltage of the IGBT is detected by an integrated short-circuit protection, which will turn off the module when a certain threshold is exceeded.

In case of short-circuit or too low supply voltage the integrated error memory is set and an error signal is generated.

The driver is connected to a controlled + 15 V-supply voltage. The input signal level is 0/15 V for the SKHI 22A/21A and 0/5 V for the SKHI 22B.

In the following explanations the whole driver family will be designated as SKHI 22B. If a special type is referred to, the concerned driver version will explicitly be named.

Technical explanations¹

Description of the circuit block diagram and the functions of the driver

The block diagram (fig.1) shows the inputs of the driver (primary side) on the left side and the outputs (secondary side) on the right.

The following functions are allocated to the primary side:

Input-Schmitt-trigger, CMOS compatible, positive logic (input high = IGBT on)

Interlock circuit and deadtime generation of the IGBT

If one IGBT is turned on, the other IGBT of a halfbridge cannot be switched. Additionally, a digitally adjustable interlocking time is generated by the driver (see fig. 3), which has to be longer than the turn-off delay time of the IGBT. This is to avoid that one IGBT is turned on before the other one is not completely discharged. This protection-function may be neutralized by switching the select input (pin6) (see fig. 3). fig. 3 documents possible interlock-times. "High" value can be achieved with no connection and connection to 5 V as well.

P6 ; SELECT	P5 ; TDT1	P9 ; TDT2	interlock time t _{TD} /µs
open / 5V	GND	GND	1,3
open / 5V	GND	open / 5V	2,3
open / 5V	open / 5V	GND	3,3
open / 5V	open / 5V	open / 5V	4,3
GND	X	X	no interlock

Fig. 3 SKHI 22B - Selection of interlock-times: „High“-level can be achieved by no connection or connecting to 5 V

Short pulse suppression

The integrated short pulse suppression avoids very short switching pulses at the power semiconductor caused by high-frequency interference pulses at the driver input signals. Switching pulses shorter than 500 ns are suppressed and not transmitted to the IGBT.

Power supply monitoring (Vs)

A controlled 15 V-supply voltage is applied to the driver. If it falls below 13 V, an error is monitored and the error output signal switches to low level.

1. The following descriptions apply to the use of the hybrid driver for IGBTs as well as for power MOSFETs. For the reason of shortness, only IGBTs will be mentioned in the following. The designations "collector" and "emitter" will refer to IGBTs, whereas for the MOSFETs "drain" and "source" are to be read instead.

Error monitoring and error memory

The error memory is set in case of under-voltage or short-circuit of the IGBTs. In case of short-circuit, an error signal is transmitted by the V_{CE} -input via the pulse transformers to the error memory. The error memory will lock all switching pulses to the IGBTs and trigger the error output (P10) of the driver. The error output consists of an open collector transistor, which directs the signal to earth in case of error. SEMIKRON recommends the user to provide for a pull-up resistor directly connected to the error evaluation board and to adapt the error level to the desired signal voltage this way. The open collector transistor may be connected to max. 30 V / 15 mA. If several SKHI 22Bs are used in one device, the error terminals may also be paralleled.

ATTENTION: Only the SKHI 22A / 21A is equipped with an internal pull-up resistor of 10 k Ω versus V_S . The SKHI 22B does not contain an internal pull-up resistor.

The error memory may only be reset, if no error is pending and both cycle signal inputs are set to low for > 9 μ s at the same time.

Pulse transformer set

The transformer set consists of two pulse transformers one is used bidirectional for turn-on and turn-off signals of the IGBT and the error feedback between primary and secondary side, the other one for the DC/DC-converter. The DC/DC-converter serves as potential-separation and power supply for the two secondary sides of the driver. The isolation voltage for the "H4"-type is 4000 V_{AC} and 2500 V_{AC} for all other types.

The secondary side consists of two symmetrical driver switches integrating the following components:

Supply voltage

The voltage supply consists of a rectifier, a capacitor, a voltage controller for - 7 V and + 15 V and a + 10 V reference voltage.

Gate driver

The output transistors of the power drivers are MOSFETs. The sources of the MOSFETs are separately connected to external terminals in order to provide setting of the turn-on and turn-off speed by the external resistors R_{ON} and R_{OFF} . Do not connect the terminals S7 with S8 and S13 with S14, respectively. The IGBT is turned on by the driver at + 15 V by R_{ON} and turned off at - 7 V by R_{OFF} . R_{ON} and R_{OFF} may not chosen below 3 Ω . In order to ensure locking of the IGBT even when the driver supply voltage is turned off, a 22 k Ω -resistor versus the emitter output (E) has been integrated at output G_{OFF} .

V_{CE} -monitoring

The V_{CE} -monitoring controls the collector-emitter voltage V_{CE} of the IGBT during its on-state. V_{CE} is internally limited to 10 V. If the reference voltage V_{CEref} is exceeded, the IGBT will be switched off and an error is indicated. The reference voltage V_{CEref} may dynamically be adapted to the IGBTs switching behaviour. Immediately after turn-on of the IGBT, a higher value is effective than in the steady state. This value will, however, be reset, when the

IGBT is turned off. V_{CEstat} is the steady-state value of V_{CEref} and is adjusted to the required maximum value for each IGBT by an external resistor R_{CE} to be connected between the terminals C_{CE} (S6/S15) and E (S9/S12). It may not exceed 10 V. The time constant for the delay of V_{CEref} may be increased by an external capacitor C_{CE} , which is connected in parallel to R_{CE} . It controls the time t_{min} which passes after turn-on of the IGBT before the V_{CE} -monitoring is activated. This makes possible any adaptation to the switching behavior of any of the IGBTs. After t_{min} has passed, the V_{CE} -monitoring will be triggered as soon as $V_{CE} > V_{CEref}$ and will turn off the IGBT.

External components and possible adjustments of the hybrid driver

Fig. 1 shows the required external components for adjustment and adaptation to the power module.

V_{CE} - monitoring adjustment

The external components R_{CE} and C_{CE} are applied for adjusting the steady-state threshold and the short-circuit monitoring dynamic. R_{CE} and C_{CE} are connected in parallel to the terminals C_{CE} (S15/ S6) and E (S12/ S9) .

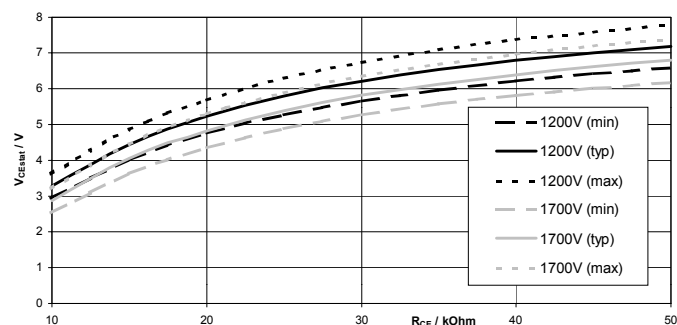


Fig. 4 V_{CEstat} in dependence of R_{CE} ($T_{amb} = 25^\circ C$)

Dimensioning of R_{CE} and C_{CE} can be done in three steps:

1. Calculate the maximum forward voltage from the datasheet of the used IGBT and determine V_{CEstat}
2. Calculate approximate value of R_{CE} according to equation (1) or (1.1) from V_{CEstat} or determine R_{CE} by using fig.4.
3. Determine t_{min} and calculate C_{CE} according to equations (2) and (3).

Typical values are

for 1200 V IGBT: $V_{CEstat} = 5$ V; $t_{min} = 1,45$ μ s,
 $R_{CE} = 18$ k Ω , $C_{CE} = 330$ pF

for 1700 V IGBT: $V_{CEstat} = 6$ V; $t_{min} = 3$ μ s,
 $R_{CE} = 36$ k Ω , $C_{CE} = 470$ pF

Adaptation to 1700 V IGBT

When using 1700 V IGBTs it is necessary to connect a 1 k Ω / 0,4 W adaptation resistor between the V_{CE} -terminal (S20/ S1) and the respective collector.

Adaptation to error signal level

An open collector transistor is used as error terminal, which, in case of error, leads the signal to earth. The signal has to be adapted to the evaluation circuit's voltage level by means of an externally connected pull-up resistor. The maximum load applied to the transistor shall be 30 V / 15 mA.

As for the SKHI 22A / 21A a 10 kΩ pull-up resistor versus V_S (P13) has already been integrated in the driver.

IGBT switching speed adjustment

The IGBT switching speed may be adjusted by the resistors R_{ON} and R_{OFF}. By increasing R_{ON} the turn-on speed will decrease. The reverse peak current of the free-wheeling diode will diminish. SEMIKRON recommends to adjust R_{ON} to a level that will keep the turn-on delay time t_{d(on)} of the IGBT < 1 μs.

By increasing R_{OFF} the turn-off speed of the IGBT will decrease. The inductive peak overvoltage during turn-off will diminish.

The minimum gate resistor value for R_{OFF} and R_{ON} is 3 Ω. Typical values for R_{ON} and R_{OFF} recommended by SEMIKRON are given in fig. 5

SK-IGBT-Modul	R _{Gon} Ω	R _{Goff} Ω	C _{CE} pF	R _{CE} kΩ	R _{VCE} kΩ
SKM 50GB123D	22	22	330	18	0
SKM 75GB123D	22	22	330	18	0
SKM 100GB123D	15	15	330	18	0
SKM 145GB123D	12	12	330	18	0
SKM 150GB123D	12	12	330	18	0
SKM 200GB123D	10	10	330	18	0
SKM 300GB123D	8,2	8,2	330	18	0
SKM 400GA123D	6,8	6,8	330	18	0
SKM 75GB173D	15	15	470	36	1
SKM 100GB173D	12	12	470	36	1
SKM 150GB173D	10	10	470	36	1
SKM 200GB173D	8,2	8,2	470	36	1

Fig. 5 Typical values for external components

Interlocking time adjustment

Fig. 3 shows the possible interlocking times between output1 and output2. Interlocking times are adjusted by connecting the terminals TDT1 (P5), TDT2 (P9) and SELECT (P6) either to earth/ GND (P7 and P14) according to the required function or by leaving them open.

A typical interlocking time value is 3,25 μs (P9 = GND; P5 and P6 open). For SKHI 22A / 21A the terminals TDT1 (P5) and SELECT (P6) are not existing. The interlocking time has been fixed to 3,25 μs and may only be increased to 4,25 μs by connecting TDT2 (P9) to V_S (P13).

ATTENTION: If the terminals TDT1 (P5), TDT2 (P9) and SELECT (P6) are not connected, eventually connected track on PC-board may not be longer than 20 mm in order to avoid interferences.

SEMIKRON recommends to start-up operation using the values recommended by SEMIKRON and to optimize the values gradually according to the IGBT switching behaviour and overvoltage peaks within the specific circuitry.

Driver performance and application limits

The drivers are designed for application with halfbridges and single modules with a maximum gate charge Q_{GE} < 4 μC (see fig. 6).

The charge necessary to switch the IGBT is mainly depending on the IGBT's chip size, the DC-link voltage and the gate voltage.

This correlation is also shown in the corresponding module datasheet curves.

It should, however, be considered that the SKHI 22B is turned on at + 15 V and turned off at - 7 V. Therefore, the gate voltage will change by 22 V during every switching procedure.

Unfortunately, most datasheets do not indicate negative gate voltages. In order to determine the required charge, the upper leg of the charge curve may be prolonged to + 22 V for determination of approximate charge per switch.

The medium output current of the driver is determined by the switching frequency and the gate charge. For the SKHI 22B the maximum medium output current is I_{outAVmax} < ± 40 mA.

The maximum switching frequency f_{MAX} may be calculated with the following formula, the maximum value however being 50 kHz due to switching reasons:

$$f_{MAX}(\text{kHz}) = \frac{4 \cdot 10^4}{Q_{GE}(\text{nC})}$$

Fig. 6 shows the maximum rating for the output charge per pulse for different gate resistors.

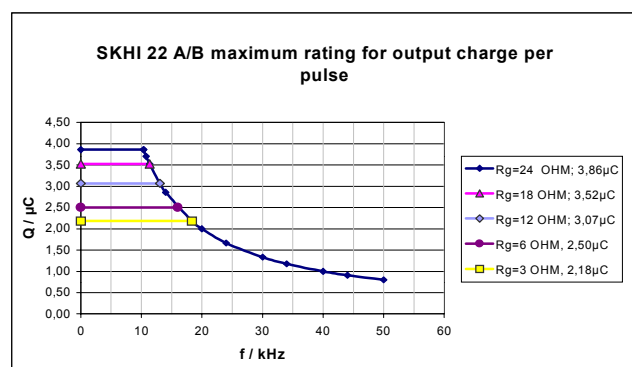


Fig. 6 Maximum rating for output charge per pulse

Further application notes

The CMOS-inputs of the hybrid driver are extremely sensitive to over-voltage. Voltages higher than V_S + 0,3 V or below - 0,3 V may destroy these inputs. Therefore, control signal over-voltages exceeding the above values have to be avoided.

Please provide for static discharge protection during handling. As long as the hybrid driver is not completely

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assembled, the input terminals have to be short-circuited. Persons working with CMOS-devices have to wear a grounded bracelet. Any synthetic floor coverings must not be statically chargeable. Even during transportation the input terminals have to be short-circuited using, for example, conductive rubber. Worktables have to be grounded. The same safety requirements apply to MOSFET- and IGBT-modules!

The connecting leads between hybrid driver and the power module should be as short as possible, the driver leads should be twisted.

Any parasitic inductances within the DC-link have to be minimized. Over-voltages may be absorbed by C- or RCD-snubbers between the main terminals for PLUS and MINUS of the power module.

When first operating a newly developed circuit, SEMIKRON recommends to apply low collector voltage and load current in the beginning and to increase these values gradually, observing the turn-off behaviour of the free-wheeling diode and the turn-off voltage spikes generated across the IGBT. An oscillographic control will be necessary. In addition to that the case temperature of the module has to be monitored. When the circuit works correctly under rated operation conditions, short-circuit testing may be done, starting again with low collector voltage.

It is important to feed any errors back to the control circuit and to switch off the device immediately in such events. Repeated turn-on of the IGBT into a short circuit with a high frequency may destroy the device.

Mechanical fixing on PCB:

In applications with mechanical vibrations (vehicles)² do not use a ty-rap for fixing the driver, but - after soldering and testing - apply special glue. Recommended types: CIBA GEIGY XP 5090 + 5091; PACTAN 5011; WACKER A33 (ivory) or N199 (transparent), applied around the case edge (forms a concave mould). The housing may not be pressed on the PCB; do not twist the PCB with the driver soldered on, otherwise the internal ceramics may crack. The driver is not suitable for big PCBs.

SEMIKRON offers a printed circuit board (PCB) type SKPC2006 compatible for mounting a SKHI 21A or SKHI 22A. This PCB contains the necessary tracks to connect the external capacitors C_{CE} and resistors R_{CE} , R_{on} , R_{off} (see fig. 1).

The PCB may directly be plugged to SEMITRANS 3-IGBT modules and be fixed to the heatsink by 3 thread bolts.

Dimensions: L x W x H = 96 x 67 x 1,5 mm.

For further details please contact SEMIKRON.

2. tested acceleration (x; y; z-axis):10-100 Hz: 1,5 g;
shock: 5 g (TÜV according to LES-DB-BN 411002)

This technical information specifies devices but promises no characteristics. No warranty or guarantee expressed or implied is made regarding delivery, performance or suitability.