

**IN THIS ISSUE**

pushbutton controller **10**

15V, 2.5A monolithic buck-boost with 95% efficiency and low noise **17**

easy 2-supply current sharing **20**

sub-1mm height 24V, 15A monolithic regulator **26**

deliver 25A at 12V from inputs to 60V **28**

## Combined Voltage and Current Control Loops Simplify LED Drivers, High Capacity Battery/Supercap Chargers & MPPT\* Solar Applications

Xin (Shin) Qi

\* Maximum Power Point Tracking

The rapid expansion of constant-current/constant-voltage (CC-CV) applications, especially in LED lighting and high capacity battery and supercapacitor chargers challenges power supply designers to keep pace with the increasingly complicated interplay of current and voltage control loops. A switch-mode converter designed specifically

for CC-CV offers a clear advantage, especially when the supply has limited power, or its power is allocated among several competing loads.

Consider, for instance, the challenge of charging a supercapacitor in a minimum amount of time from a *power-limited* supply. To maintain constant input power, the controlled charging current must decrease as the output (supercapacitor) voltage increases. The LT<sup>®</sup>3796 solves the problem of power limited or constant current/constant voltage regulation by seamlessly combining a current regulation loop and two voltage regulation loops to control an external N-channel power switch. The inherent wired-OR behavior of its three transconductance error amplifiers summed into the compensation pin,  $V_C$ , ensures that the correct loop (that is, the one closest to regulation) dominates.

(continued on page 4)



The LTC4155 is a monolithic switching battery charger that efficiently delivers 3.5A charge current in a compact PCB footprint. See page 13.

The LT3796's wide  $V_{IN}$  range (6V to 100V) and rail-to-rail (0V to 100V) output current monitoring and regulation allow it to be used in a wide variety of applications from solar battery chargers to high power LED lighting systems.

(LT3796, continued from page 1)

The additional, standalone current sense amplifier can be configured for any number of functions, including input current limit and input voltage regulation.

The LT3796's wide  $v_{IN}$  range (6V to 100V) and rail-to-rail (0V to 100V) output current monitoring and regulation allow it to be used in a wide variety of applications from solar battery chargers to high power LED lighting systems. The fixed switching frequency, current-mode architecture results in stable operation over a wide range of supply and output voltages. The LT3796 incorporates a high side current sense, enabling its use in boost, buck, buck-boost or SEPIC and flyback topologies.

### HIGH POWER LED DRIVER WITH ROBUST OUTPUT SHORT CIRCUIT PROTECTION

Figure 1 shows the LT3796 configured as a boost converter to drive a 34W LED string from a wide input range. The LED current is derated at low input voltages to prevent external power components from overheating. The front-end current sense amplifier monitors the input current by converting the input current to a voltage signal at the CSOUT pin with

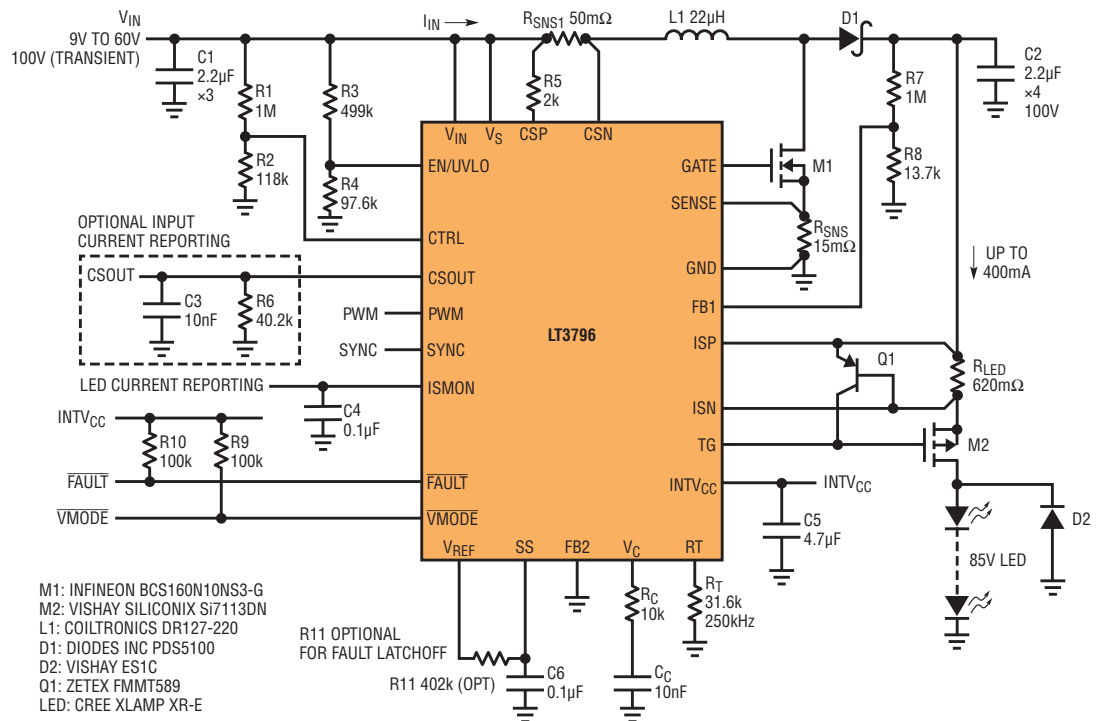
$$V_{CSOUT} = I_{IN} \cdot R_{SNS1} \cdot \frac{R6}{R5}$$

The resistor network at the FB1 pin provides OPENLED protection, which limits the output voltage and prevents the ISP pin, ISN pin and several external

components from exceeding their maximum rating. If an LED fails open or if the LED string is removed from the high power driver, the FB constant voltage loop takes over and regulates the output to 92.5V. The  $\overline{VMODE}$  flag is also asserted to indicate an OPENLED event.

The LT3796 includes short-circuit protection independent of the LED current sense. The short-circuit protection feature prevents the development of excessive switching currents and protects the power components. The protection threshold (375mV, typ) is designed to be 50% higher than the default LED current sense threshold.

Figure 1. A 34W LED driver with robust output short-circuit protection.



The LT3796 solves the problem of power limited, or constant-current/constant-voltage regulation by seamlessly combining a current regulation loop and two voltage regulation loops to control an external N-channel power switch.

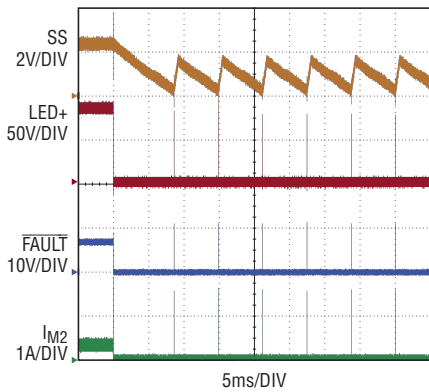


Figure 2. Short LED protection: hiccup mode (without R11 in Figure 1)

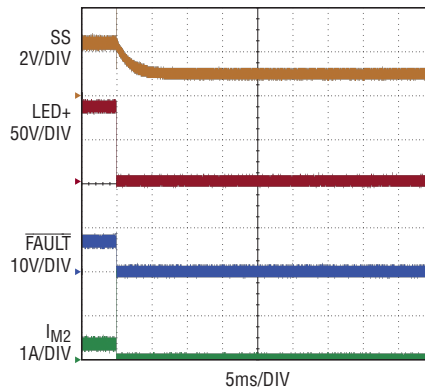


Figure 3. Short LED protection: latching mode (with R11 in Figure 1)

Once the LED overcurrent is detected, the GATE pin drives to GND to stop switching, the TG pin is pulled high to disconnect the LED array from the power path and the FAULT pin is asserted. The Schottky diode D2 is added to protect

the drain of PMOS M2 from swinging well below ground when shorting to ground through a long cable. The PNP helper Q1 is included to further limit the transient short-circuit current.

If there is no resistor between the ss pin and V<sub>REF</sub> pin, the converter enters hiccup mode and periodically retries as shown in the Figure 2. If a resistor is placed between V<sub>REF</sub> and ss pin to hold ss pin higher than 0.2V during LED short, then the LT3796 enters latching mode with GATE pin low and TG pin high, as shown in Figure 3. To exit latching mode, the EN/UVLO pin must be toggled low to high.

**LED DRIVER WITH HIGH PWM DIMMING RATIO**

Using an input referred LED string allows the LT3796 to act as a buck mode controller as shown in Figure 4. The 1MHz operating frequency enables a high PWM dimming ratio. The OPENLED regulation voltage is set to

$$1.25V \cdot \frac{R3}{R6} \cdot \left( \frac{R5}{R4} + 1 \right)$$

through the independent current sense amplifier at CSP, CSN and CSOUT pins. During the PWM off phase, the LT3796 disables all internal loads to the V<sub>C</sub> pin

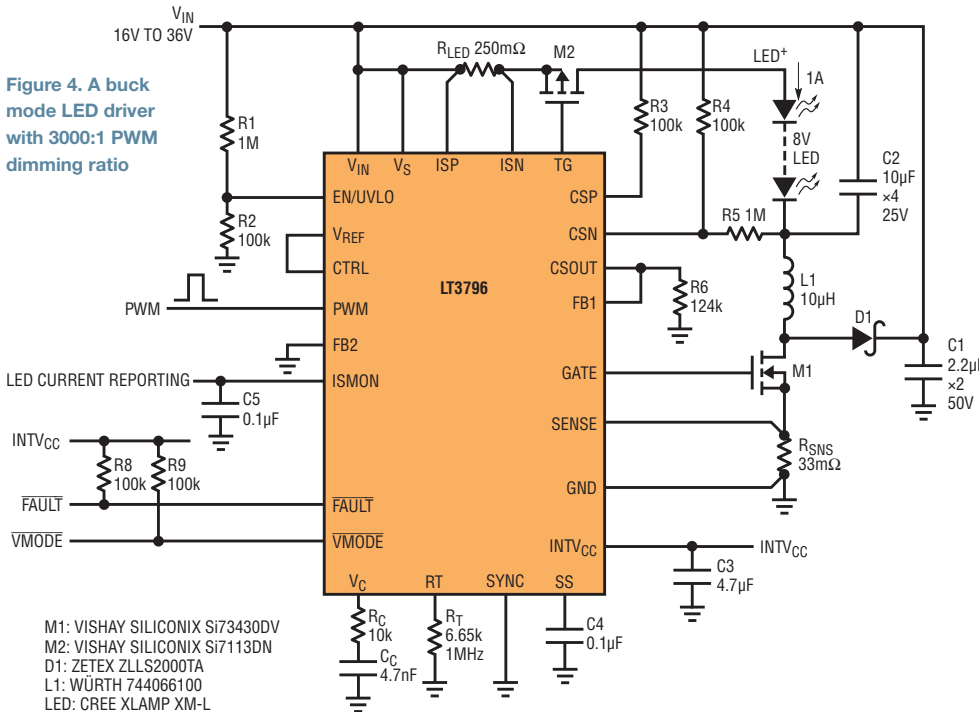
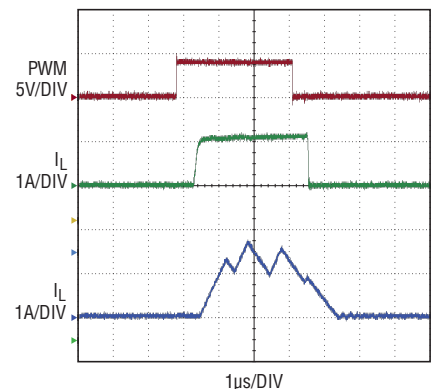
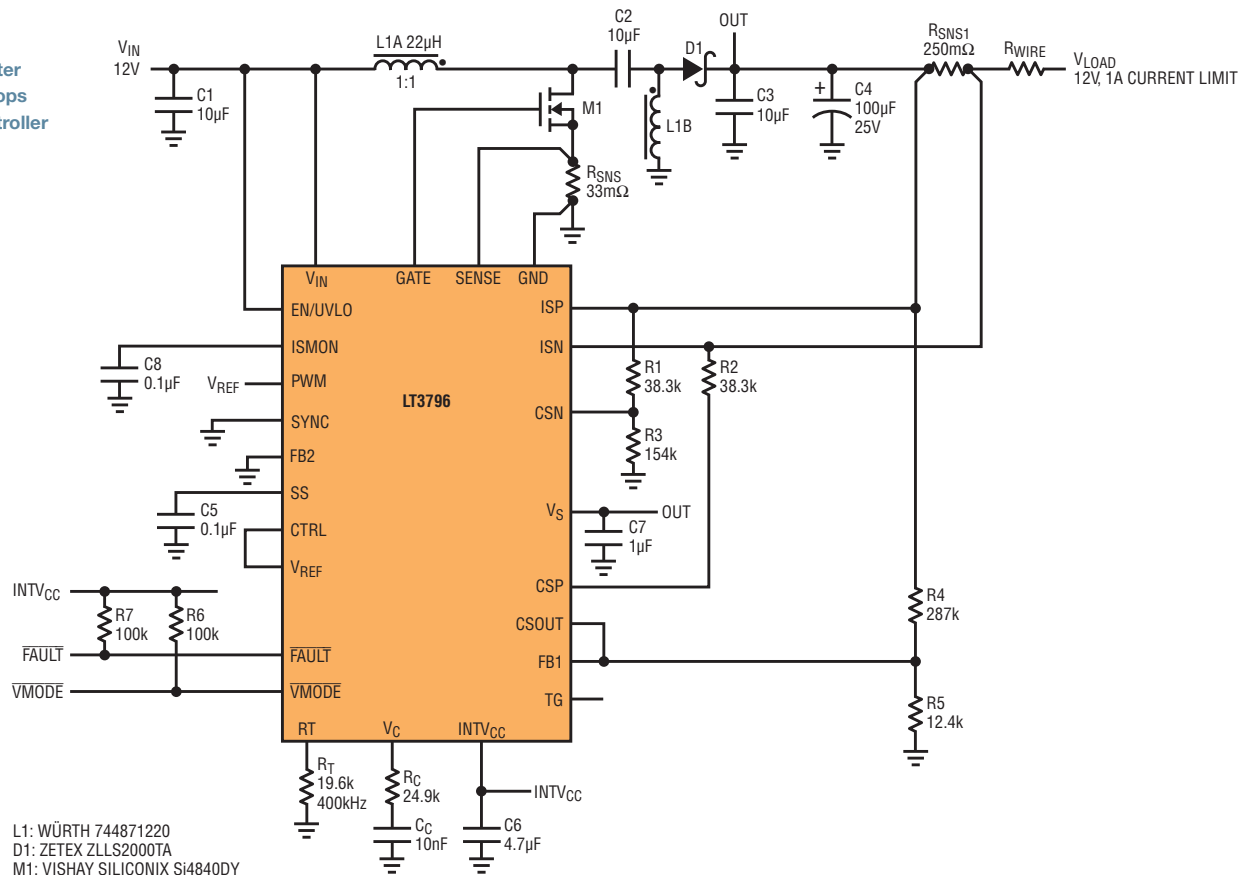


Figure 5. 3000:1 PWM dimming ratio of the circuit in Figure 4 at V<sub>IN</sub> = 24V and PWM = 100Hz



Voltage drops in wiring and cables can cause load regulation errors. These errors can be corrected by adding remote sensing wires, but adding wires is not an option in some applications. As an alternative, the LT3796 can adjust for wiring drops, regardless of load current, provided that the parasitic wiring or cable impedance is known.

Figure 6. This SEPIC converter compensates for voltage drops in the wire between the controller and the load ( $R_{WIRE}$ )



and preserves the charge state. It also turns off the PMOS switch M2 to disconnect the LED string from the power path and prevent the output capacitor from discharging. These features combine to greatly improve the LED current recovery time when PWM signal goes high. Even with a 100Hz PWM input signal, this buck mode LED driver can achieve a 3000:1 dimming ratio as illustrated in Figure 5.

### SEPIC CONVERTER WITH $R_{WIRE}$ COMPENSATION

Voltage drops in wiring and cables can cause load regulation errors. These errors can be corrected by adding remote sensing wires, but adding wires is not an option in some applications. As an alternative, the LT3796 can adjust for wiring drops, regardless of load current, provided that the parasitic wiring or cable impedance is known.

Figure 6 shows a 12V SEPIC converter that uses the  $R_{WIRE}$  compensation feature.  $R_{SENS1}$  is selected to have 1A load current

limit controlled by the ISP, ISN pins. The resistor network R1–R5, along with the LT3796’s integrated current sense amplifier (CSAMP in Figure 7), adjusts the OUT node voltage ( $V_{OUT}$ ) to account for voltage drops with respect to the load current. This ensures that  $V_{LOAD}$  remains constant at 12V throughout the load range.

Figure 7 shows how the LT3796’s internal CSAMP circuit plays into the operation. The LT3796’s voltage loop regulates the FB1 pin at 1.25V so that  $I_3$  stays fixed at 100µA for  $R_5 = 12.4k$ . In Figure 7,  $V_{OUT}$  changes

The LT3796 in a 28-lead TSSOP package performs tasks that would otherwise require a number of control ICs and systems. It offers a reliable power system with simplicity, reduced cost and small solution size.

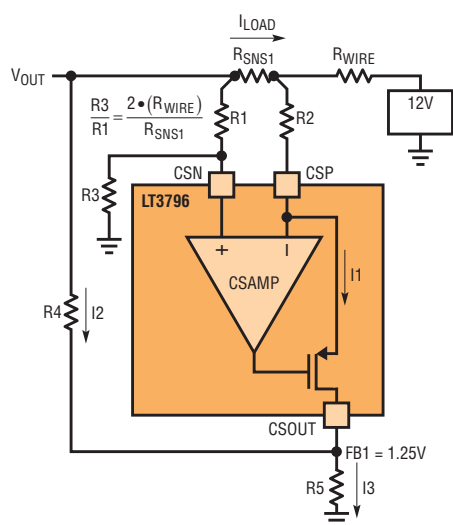


Figure 7.  $R_{WIRE}$  voltage drops are compensated for via the LT3796's CSAMP circuit

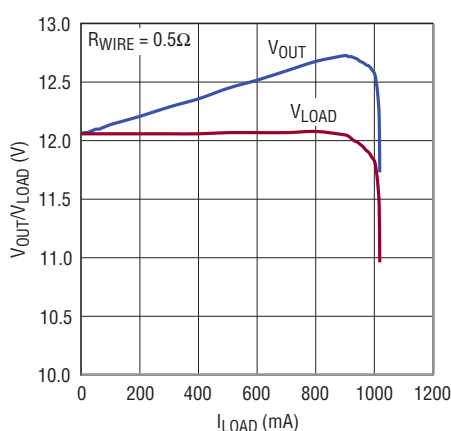


Figure 8. Measured  $V_{LOAD}$  and  $V_{OUT}$  with respect to  $I_{LOAD}$

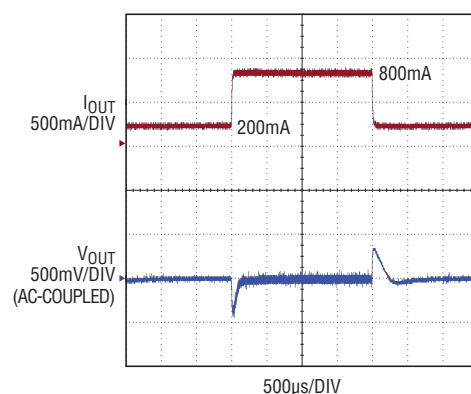


Figure 9. Load step response of the circuit in Figure 6

with current  $I_2$  as  $V_{OUT} = 1.25V + I_2 \cdot R_4$ . If the change of  $I_2 \cdot R_4$  can offset the change of  $I_{LOAD} \cdot (R_{SNS1} + R_{WIRE})$ , then  $V_{LOAD}$  will stay constant.

Referring to Figure 7, the divider  $R1/R3$  from  $V_{OUT}$  sets the voltage regulated at CSP by the current  $I_1$  flowing in  $R2$ .  $I_1$  is conveyed to the FB1 node where it sums with  $I_2$ .

As the output current increases,  $I_1$  decreases due to the increasing voltage drop across  $R_{SNS1}$ ; its decrease must be compensated by a matching increase in the current  $I_2$  to maintain the constant 100 $\mu$ A into FB2. This increase in  $I_2$  with

output current is what gives  $V_{OUT}$  the positive load regulation characteristic. The positive load regulation is just what is needed to compensate for the cable drop.

The measured  $V_{LOAD}$  and  $V_{OUT}$  with respect to  $I_{LOAD}$  are shown in Figure 8. Clearly,  $V_{LOAD}$  is independent of  $I_{LOAD}$  when  $I_{LOAD}$  is less than the 1A current limit. When  $I_{LOAD}$  approaches 1A, the current loop at ISP and ISN pins begins to interfere with the voltage loop and drags the output voltage down correspondingly. The load transient response is shown in Figure 9.

### SOLAR PANEL BATTERY CHARGER

Solar powered devices rely on a highly variable energy source, so for a device to be useful at all times, energy from solar cells must be stored in a rechargeable battery. Solar panels have a maximum power point, a relatively fixed voltage at which the panel can produce the most power. Maximum power point tracking (MPPT) is usually achieved by limiting a converter's output current to keep the panel voltage from straying from this value. The LT3796's unique combination of current and voltage loops make it an ideal MPPT battery charger solution.

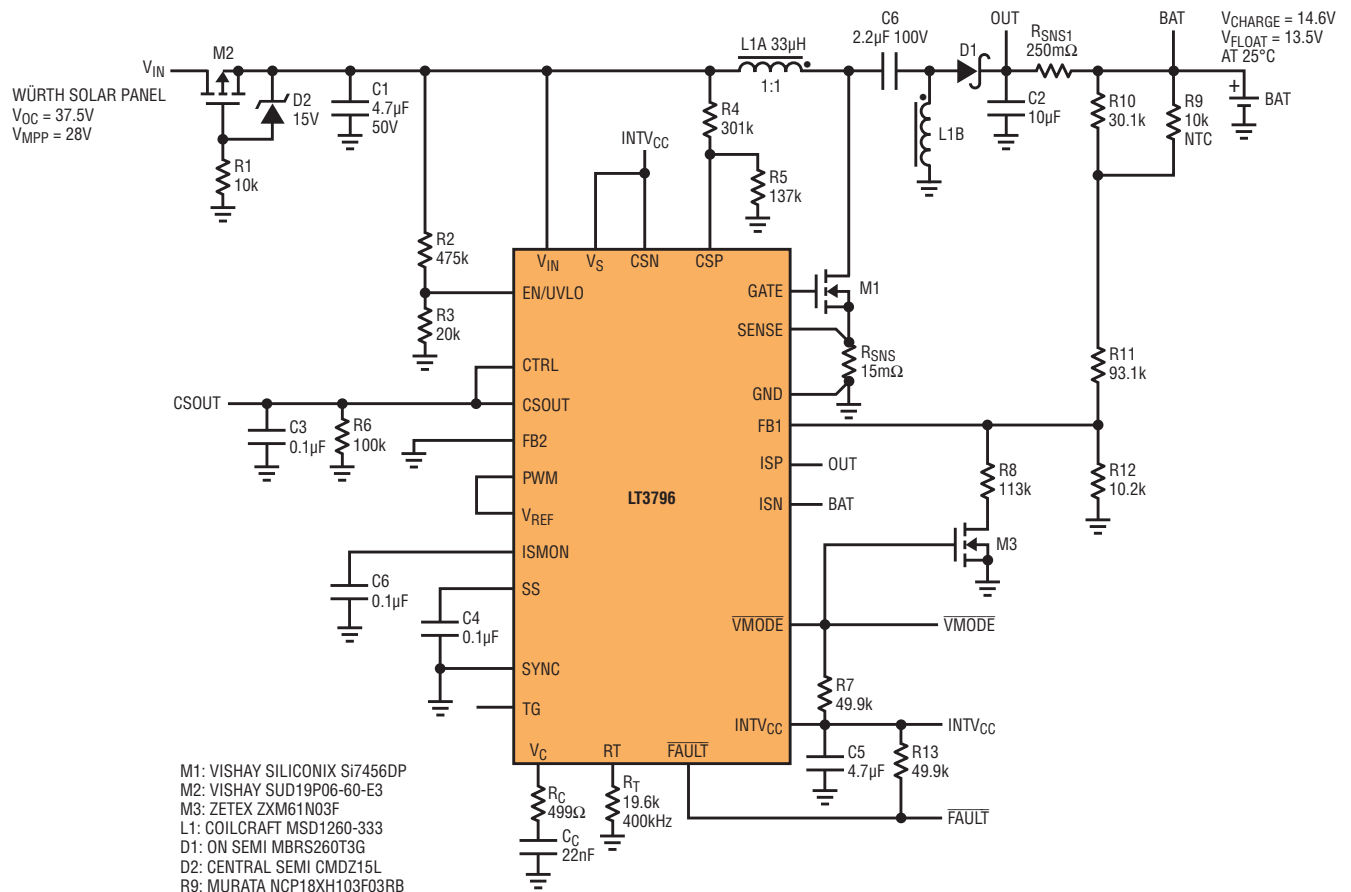


Figure 10. A solar panel battery charger maximum power point tracking (MPPT)

Figure 10 shows a solar panel to sealed lead acid (SLA) battery charger driven by the LT3796. The charger uses a three-stage charging scheme. The first stage is a constant current charge. Once the battery is charged up to 14.35V, the charging current

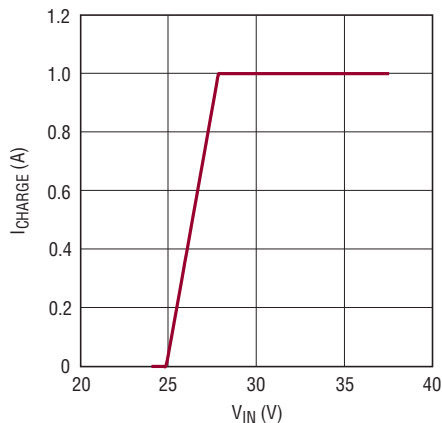


Figure 11. I<sub>CHARGE</sub> vs V<sub>IN</sub> for the solar charger in Figure 10

begins to decrease. Finally, when the required battery charge current falls below 100mA, the built-in C/I0 termination disables the charge circuit by pulling down  $\overline{VMODE}$ , and the charger enters float charge stage with  $V_{FLOAT} = 13.5V$  to compensate for the loss caused by self-discharge.

The charging current is programmed by the resistor network at the CSP and CSOUT (CTRL) pins as follows,

$$V_{CTRL} = R_6 \cdot \left( \frac{V_{IN} - V_{INTVCC}}{R_4} - \frac{V_{INTVCC}}{R_5} \right)$$

$$\text{FOR } V_{IN} \geq V_{INTVCC} \left( 1 + \frac{R_4}{R_5} \right)$$

$$V_{CTRL} = 0V,$$

$$\text{FOR } V_{IN} < V_{INTVCC} \left( 1 + \frac{R_4}{R_5} \right)$$

Maximum power point tracking is implemented by controlling the maximum output charge current. Charge

current is reduced as the voltage on the solar panel output falls toward 28V, which corresponds to 1.1V on the CTRL pin and full charging current, as shown in Figure 11. This servo loop thus acts to dynamically reduce the power requirements of the charger system to the maximum power that the panel can provide, maintaining solar panel power utilization close to 100%.

### SUPERCAPACITOR CHARGER WITH INPUT CURRENT LIMIT

Supercapacitors are rapidly replacing batteries in a number of applications from rapid-charge power cells for cordless tools to short term backup systems for microprocessors. Supercapacitors are longer lasting, greener, higher performance and less expensive over the long run, but charging supercapacitors requires precise control of charging current and voltage

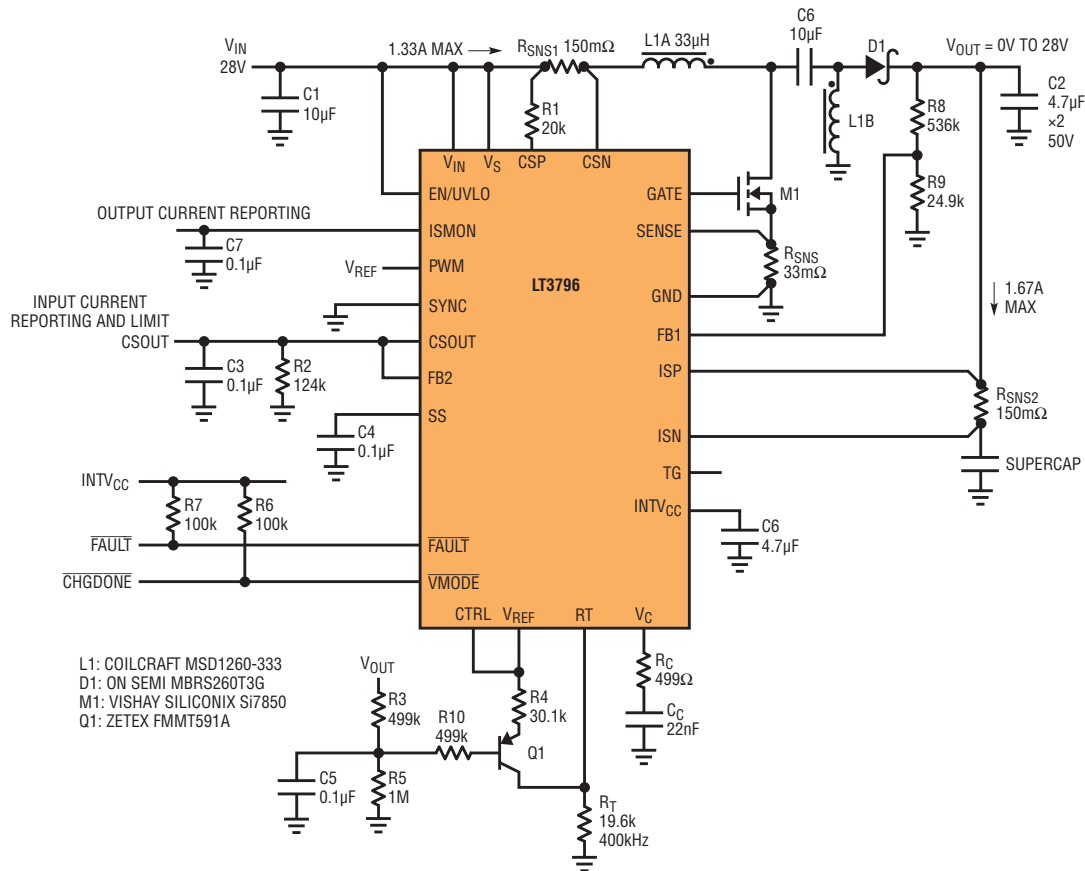


Figure 12. A 28V/1.67A supercapacitor charger with input current limit

limiting to prevent any system-wide damage or damage to the supercapacitor.

Some applications require that the input current is limited to prevent the input supply from crashing. Figure 12 shows a 1.67A supercapacitor charger with 28V regulated output voltage and 1.33A input current limit. The input current is sensed by  $R_{SNS1}$ , converted to a voltage signal and fed to the FB2 pin to provide input current limit.

In each charging cycle, the supercapacitor is charged from 0V. The feedback loop from  $V_{OUT}$  to the RT pin through  $R_3$ ,  $C_5$ ,  $R_5$ ,  $R_{10}$ ,  $R_4$ , and  $Q_1$  to  $R_T$  works as frequency foldback to keep regulation under control. In Figure 13, the input current and output current are plotted against output voltage for this charger, showing the LT3796 maintaining the output current

regulation until the input current moves close to the 1.33A input current limit.

### CONCLUSION

The LT3796 is a versatile step-up DC/DC controller that combines accurate current and voltage regulation loops. Its unique combination of a single current loop and two voltage loops makes it easy to solve the problems posed by applications that require multiple control loops, such as LED drivers, battery or supercapacitor chargers, MPPT solar battery chargers, and step-up or SEPIC converters with input and output current limit. It also includes a number of fault protection and reporting functions, a top gate driver and current loop reporting.

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and systems. It offers a reliable power system with simplicity, reduced cost and small solution size. ■

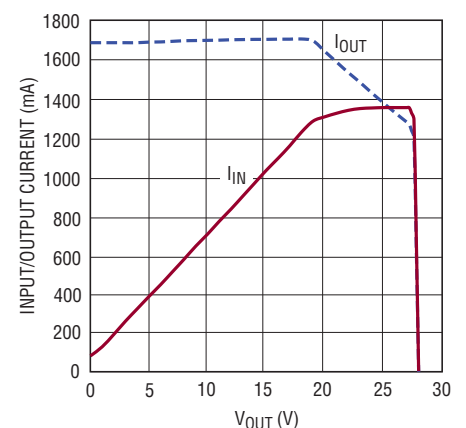


Figure 13. Input/output current vs output voltage for 28V/1.67A supercapacitor charger in Figure 12